

Subdivision of A-Splines

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What is an A-spline?

- “Algebraic spline”
- Implicit polynomial curve $f(x, y) = 0$ in compact domain.
- We’ll focus on planar, *triangular* A-splines.

Motivation

- Quickly draw curves and surfaces
- Implicit form easy to derive, manipulate
- Implicit form hard to render
- Until I show you what I got...

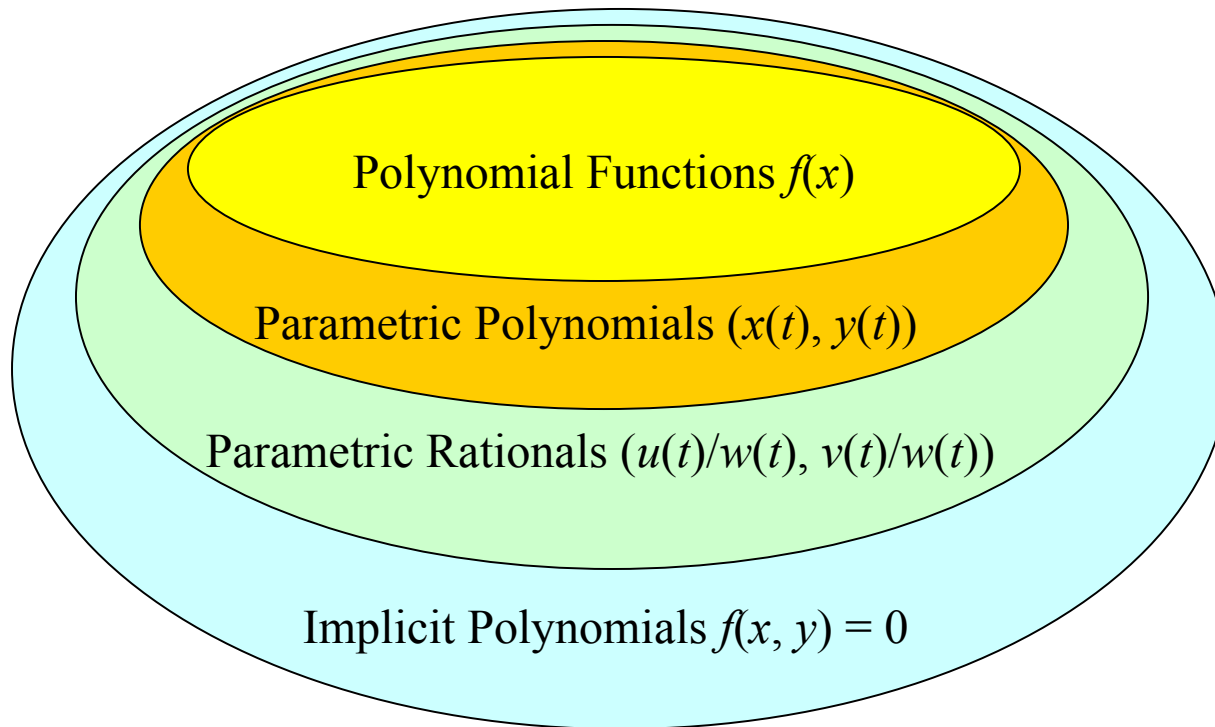
The Problem

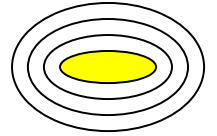
- Given description of image A
- Find:
 - Initial set A_0
 - Function S
- Such that $A_0, S(A_0), S^2(A_0), \dots \xrightarrow{\text{quickly}} A$.

The Solution: Subdivision

- Start with A_0 = a “control polygon”
- Subdivision function S splits polygons into subpolygons.
- Define S so that convergence is fast.

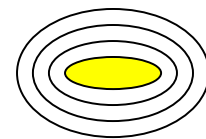
What can we subdivide?



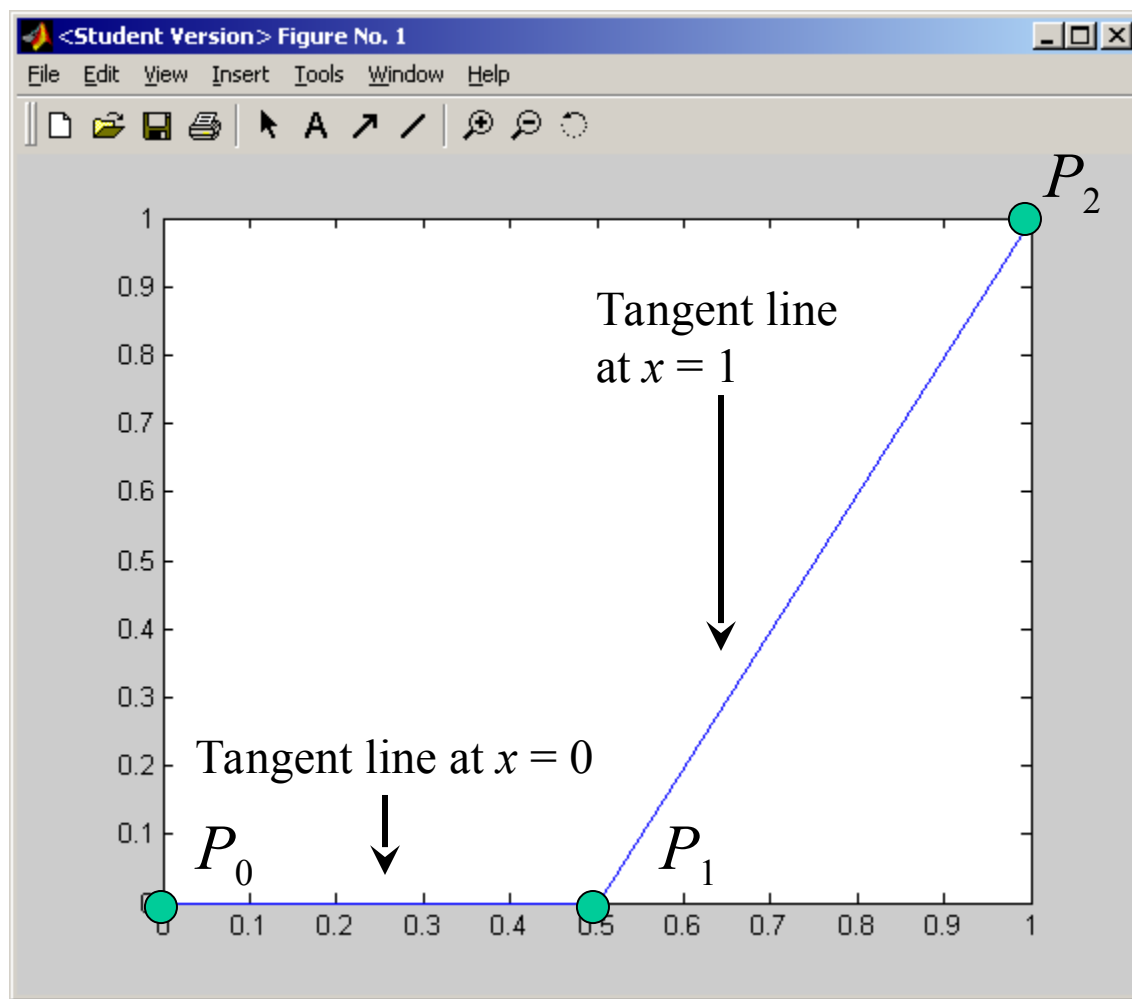


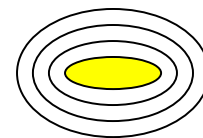
Polynomial Functions

- Want to graph $f(x) = x^2$ over $[0, 1]$
- We'll use *subdivision*.
- de Casteljau Algorithm, Bézier curve

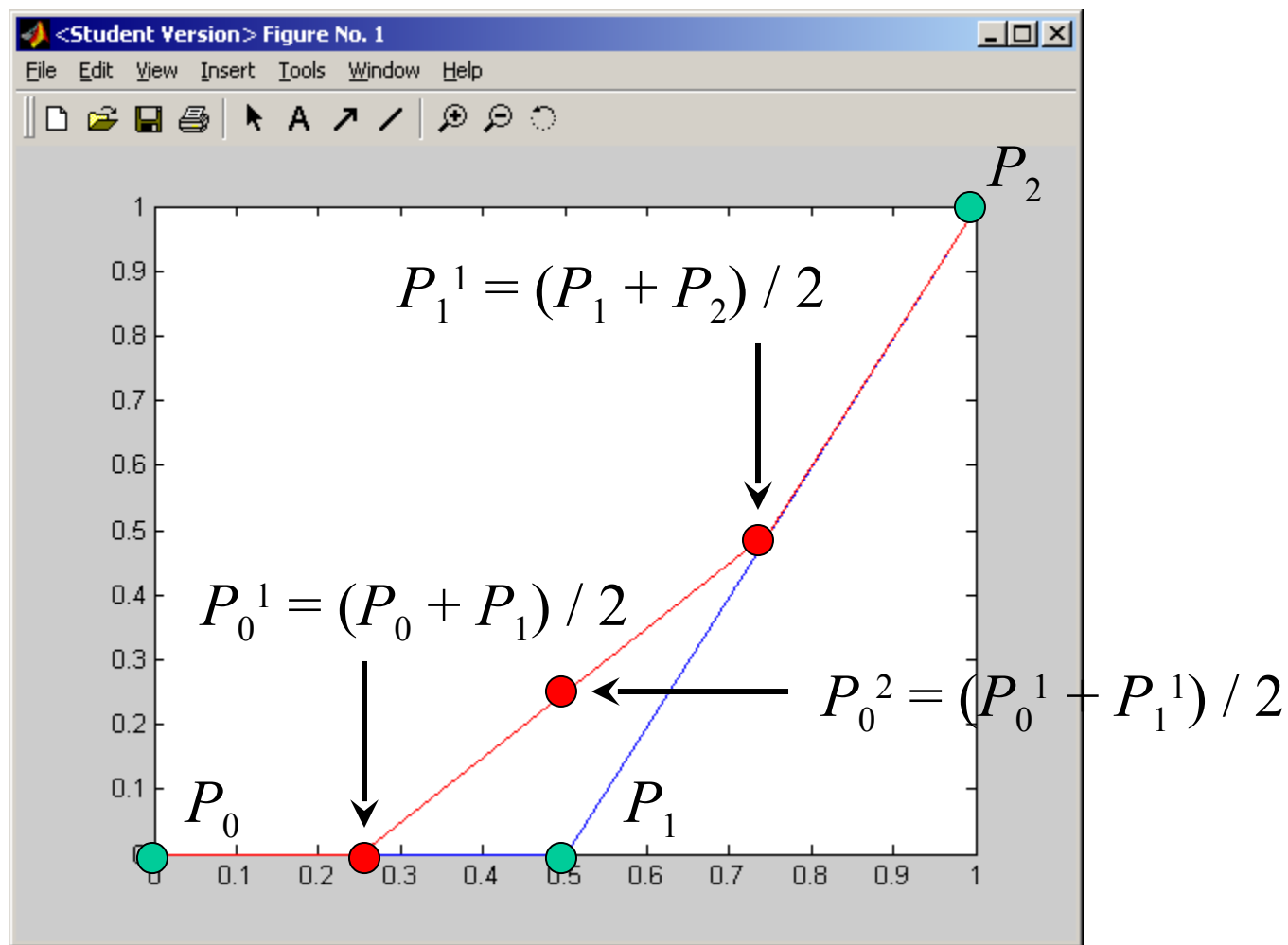


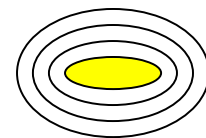
Polynomial Function Subdivision



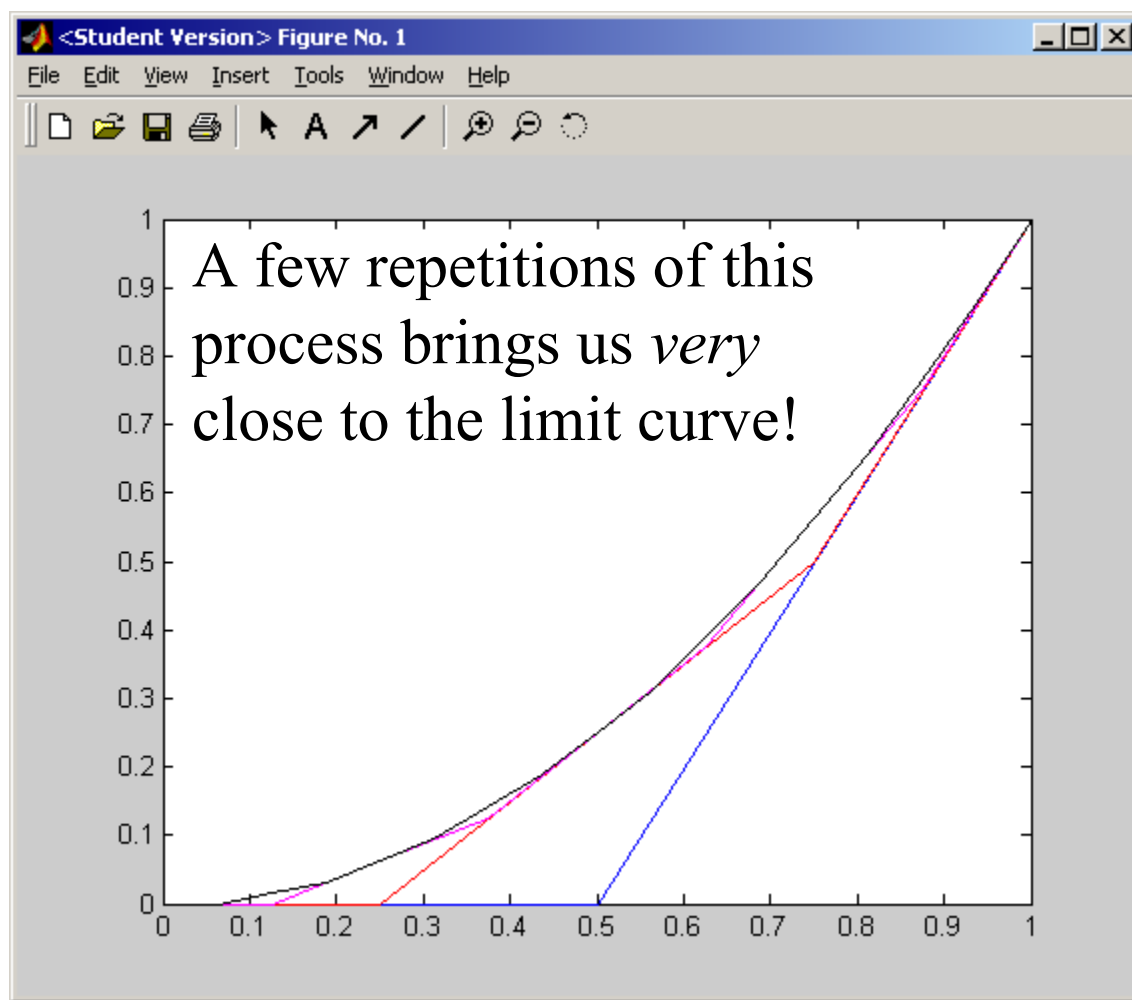


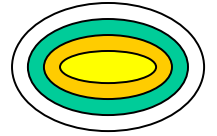
Polynomial Function Subdivision





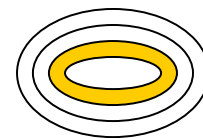
Polynomial Function Subdivision



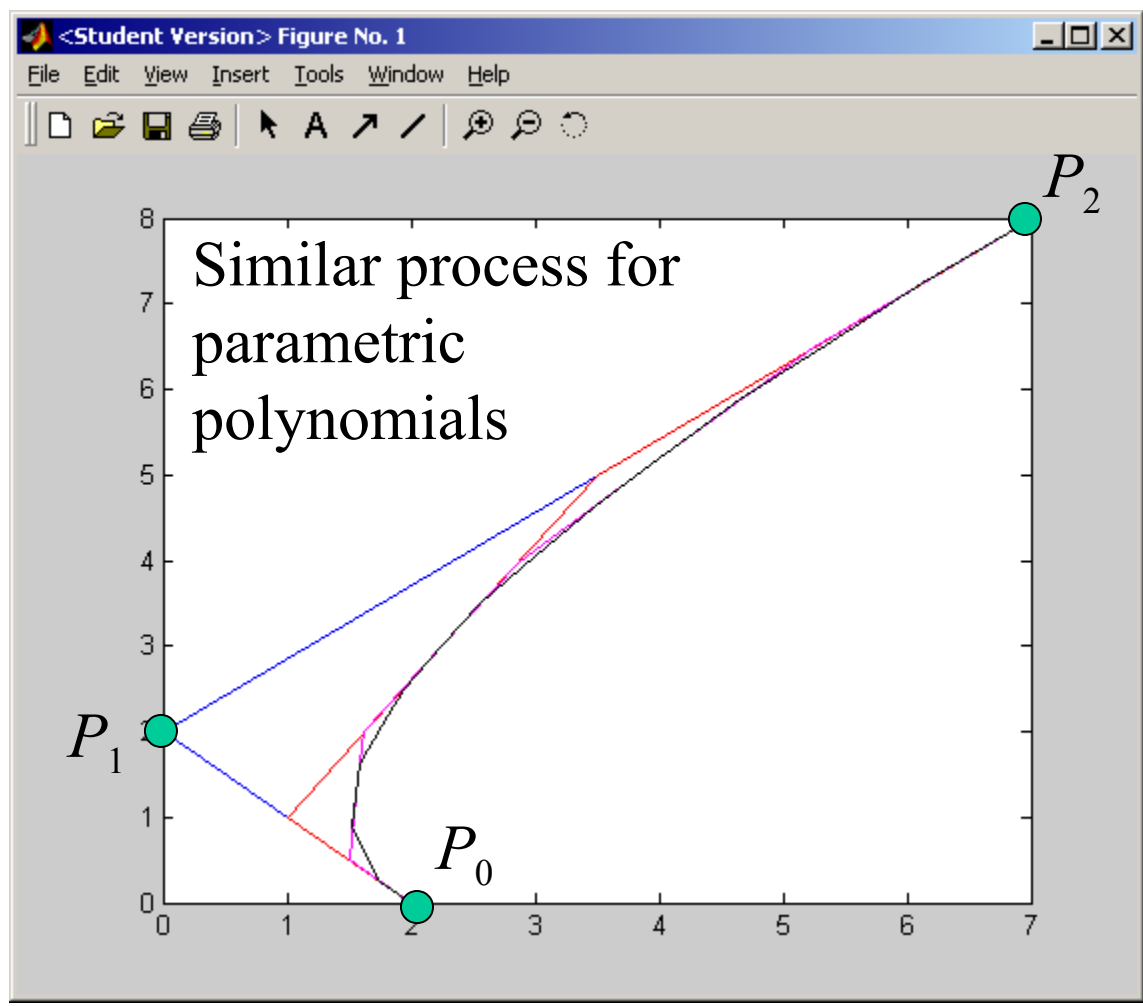


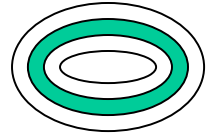
Complexity of Subdivision

- $O(2^N d^2)$ where:
- Subdivision is iterated N times
- Curve has degree d



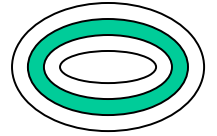
Parametric Polynomials





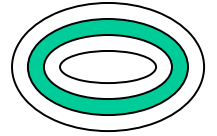
Parametric Rationals

- Projection of a polynomial curve in \mathbf{R}^3
- Subdivision algorithm: Subdivide polynomial curve in \mathbf{R}^3 and project down to \mathbf{R}^2 (Rational de Casteljau Algorithm)



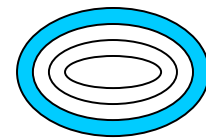
How can we describe rationals?

- Rational parametric form
 - $(u(t)/w(t), v(t)/w(t))$, where u, v, w polynomials
- Rational implicit form
 - $f(x, y) = 0$, where f polynomial



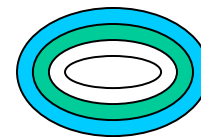
Parametric vs. Implicit

- Implicit form
 - Hard, slow to render
 - Easy to compute with (offset, intersection)
- Parametric form
 - Easy, fast to render
 - Harder to compute with
- Rationals: both forms, both advantages



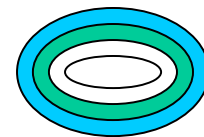
Algebraic Plane Curves

- Implicit polynomial $f(x, y) = 0$
- Want to subdivide algebraic plane curves.
- How?
- Idea: find rational parameterization!



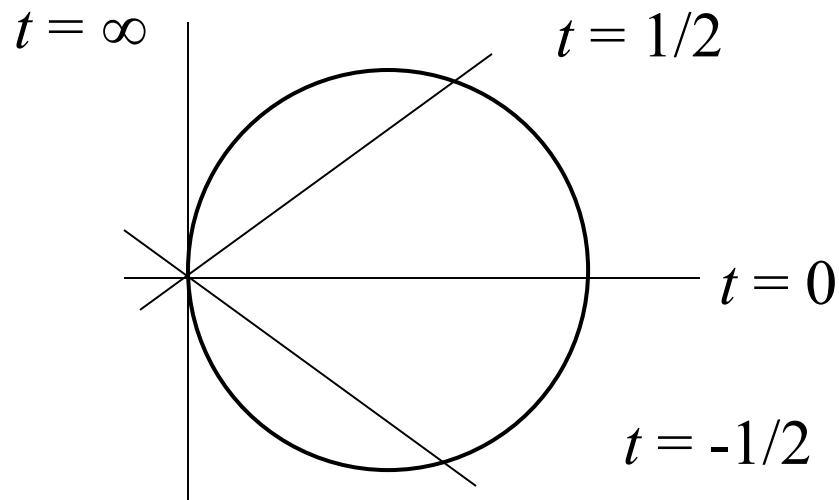
Rational Parameterization

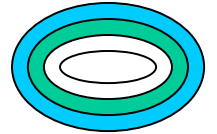
- Not all algebraic curves are rational.
- How do we tell if a given curve is rational?
- Cayley-Riemann Theorem:
 - $Genus = 0 \Leftrightarrow$ curve is rational
- Compute genus: if genus = 0, it is rational!



Rational Parameterization

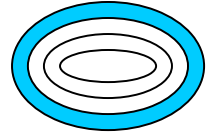
- So, given a rational algebraic curve:
- Find rational parameterization with pencil of lines





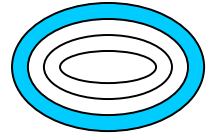
Complexity of Parameterization

- $O(d^6 \log^3 d + d^2 T(d^2))$
- $T(d) = O(d^3 \log^2 d + d^2 \log d \log(1/\varepsilon))$
- $T(d)$ is the time to solve one-variable implicit polynomial equation of degree d with precision ε



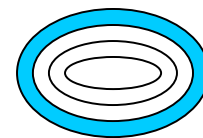
We ignored the irrational ones!

- Let's find a more general technique.
- Planar, triangular *A-splines*:
 - Algebraic plane curves
 - Restricted to a triangle $\Delta P_1 P_2 P_3$
 - Curve passes through P_1 and P_2



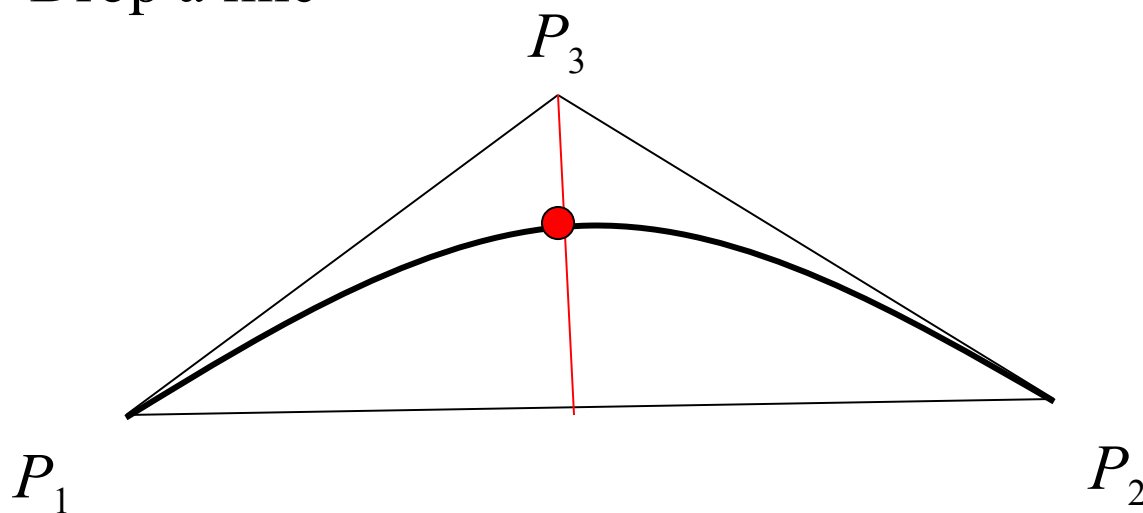
Convex A-Splines

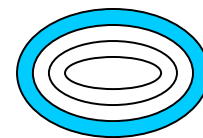
An A-spline is *convex* if it has no inflection points within its triangle.



Subdividing Convex A-Splines

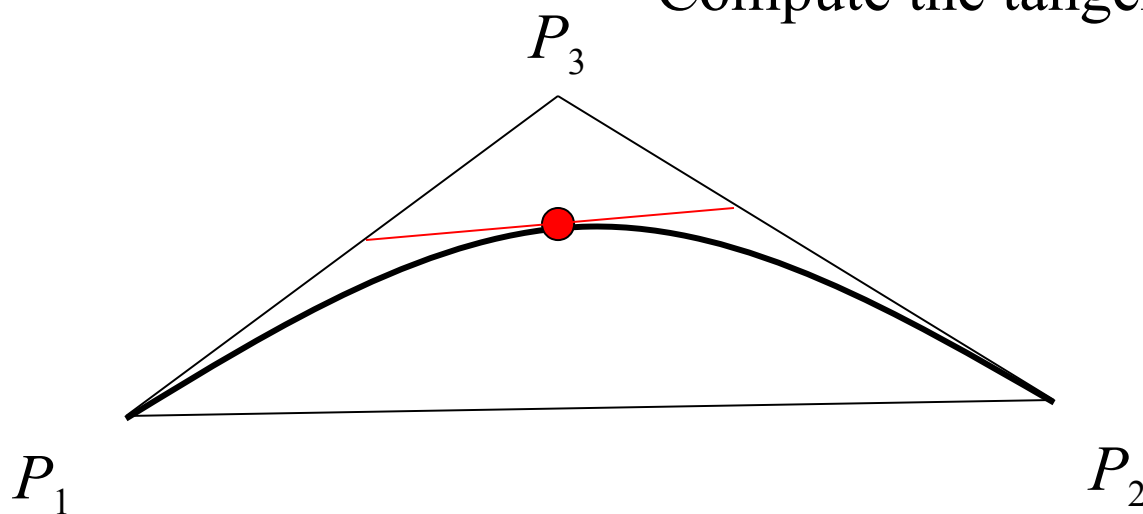
Drop a line

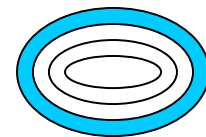




Subdividing Convex A-Splines

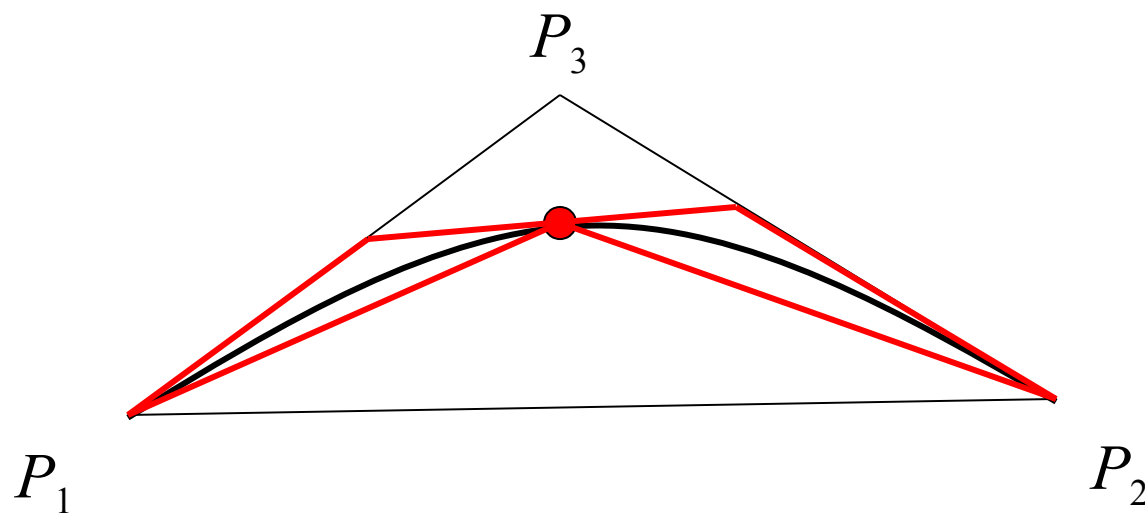
Compute the tangent



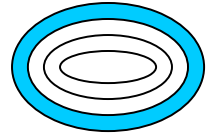


Subdividing Convex A-Splines

We have two new triangles!
One step of subdivision is complete!

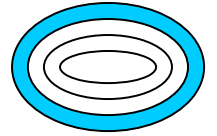


Repeat to subdivide more.



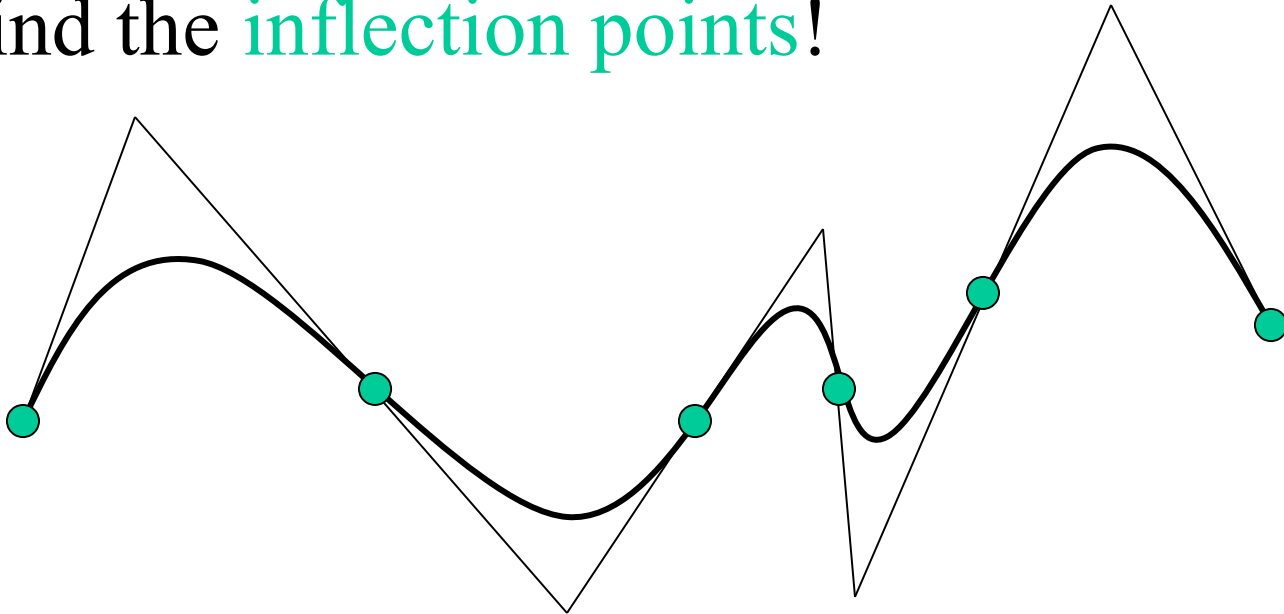
Subdividing A-Splines

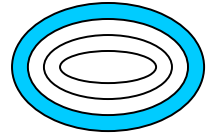
- How would we subdivide A-splines which are not convex?
- How about:
 - Divide A-spline into convex pieces
 - Subdivide each piece!



Subdividing A-Splines

- How do we divide an A-spline into convex pieces?
- Find the **inflection points**!



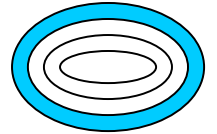


Finding Inflection Points

- Compute Hessian:

$$H(x, y) = \begin{vmatrix} f_{xx} & f_{xy} & f_{xz} \\ f_{yx} & f_{yy} & f_{yz} \\ f_{zx} & f_{zy} & f_{zz} \end{vmatrix} = 0$$

- Solve $f(x, y) = H(x, y) = 0$
- Theorem:
 - solutions = {inflection points, singularities}



Finding Inflection Points

- Compute singularities:

$$f(x, y) = f_x(x, y) = f_y(x, y) = 0$$

- Subtract singularities from previous solution:

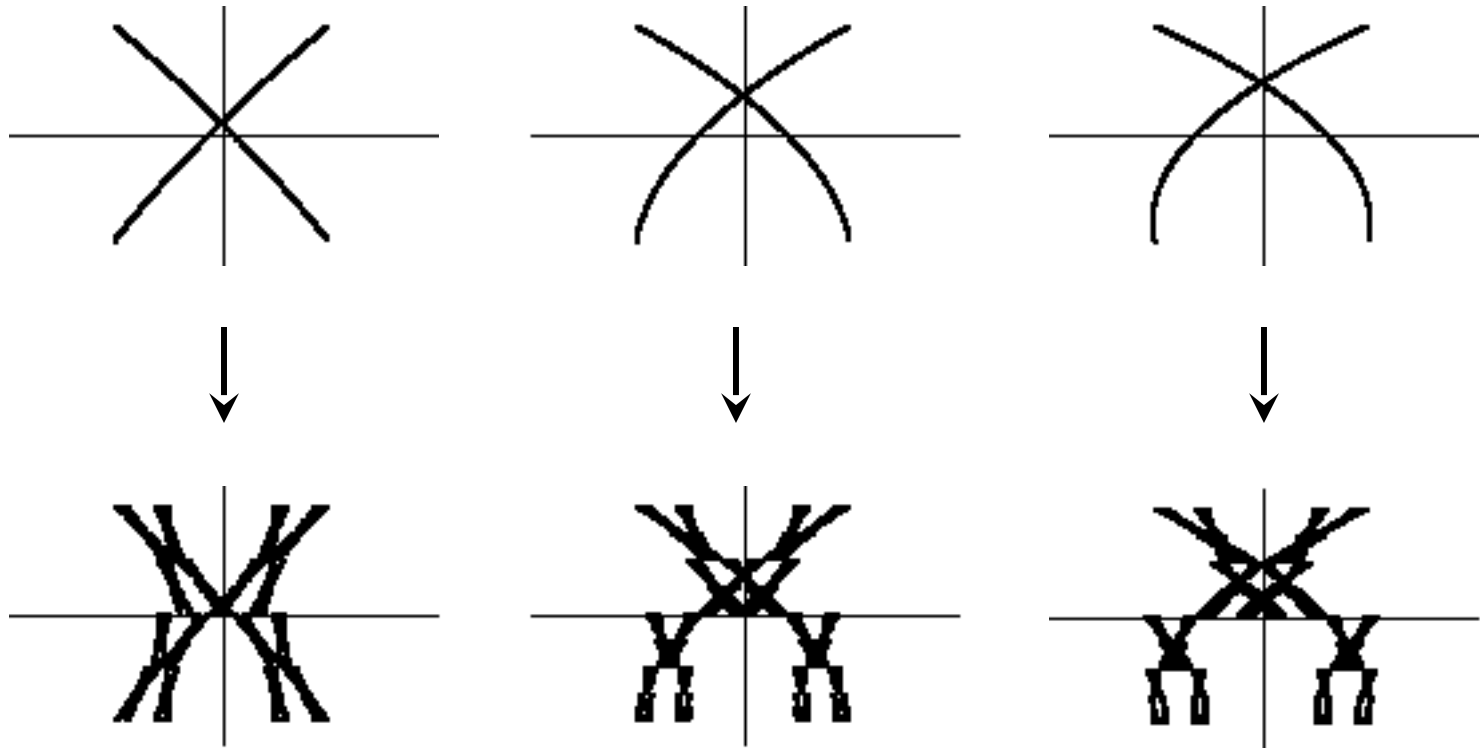
$$\{\text{inflections, singularities}\} - \{\text{singularities}\} = \{\text{inflections}\}!$$

- Thus we can subdivide *all* A-splines!
- $O(2^N d^6 \log^3 d + 2^N d^2 T(d) + T(d^2))$

Further Study: A-Patches

- How about surfaces?
- A-patches (algebraic patches):
 - $f(x, y, z) = 0$ in compact domain
 - Surface of revolution subdivision is already implemented in GANITH
 - Sweeping, lofting A-splines is next

Further Study: Control Fractals



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